

60965 Conversion Decoder Set for a Steam Locomotive 60966 Conversion Decoder Set for a Diesel Locomotive 60967 Conversion Decoder Set for a Electric Locomotive

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Using the Product as Intended

The 60965/60966/60967 decoders are for converting Märklin/Trix H0 locomotives to digital.

! Not suitable for motors with field-wound coils. Locomotives with these motors must be converted with the appropriate motor retrofit kits, item numbers 60941, 60943, or 60944.

! Important: The following locomotives (locomotive-specific decoder) cannot be converted with this decoder.

Item:

| 26410 | 37346 | 37777 | 39340 |
|-------------------|-------|-------|-------|
| 26453 | 37403 | 37786 | 39343 |
| 26490 | 37404 | 37787 | 39390 |
| 26557 | 37435 | 37790 | 39392 |
| 26561 | 37485 | 37791 | 39393 |
| 26562 | 37501 | 37867 | 39399 |
| 29094 (onlyE 94) | 37504 | 37940 | 39404 |
| 29440 (only E 10) | 37505 | 37941 | 39441 |
| 29500 (only E 50) | 37530 | 37993 | 39563 |
| 37010 | 37542 | 39014 | 39564 |
| 37011 | 37573 | 39022 | 39565 |
| 37044 | 37574 | 39051 | 39643 |
| 37226 | 37575 | 39081 | 39836 |
| 37227 | 37580 | 39110 | 39837 |
| 37239 | 37581 | 39123 | 39838 |
| 37274 | 37607 | 39140 | 39896 |
| 37275 | 37733 | 39185 | 39972 |
| 37321 | 37734 | 39303 | 39986 |

Contents as Delivered

- 1 decoder
- 1 circuit board with a 8-pin connector
- 1 speaker small
- 1 speaker big
- 1 adhesive pad
- Installation instructions
- Warranty card

Tools also needed for the installation procedure include: regular and cross-point screwdrivers, tweezers, and soldering station with a maximum soldering temperature of up to 30 watts / 300°Celsius / 572°Fahrenheit with a fine tip, soldering flux for electronics (0.5 - 1 mm / $0.02^{"} - 0.04^{"}$ diameter), desoldering braid or a de-soldering pump.

Safety Notes

- WARNING! Sharp edges and points required for operation.
- Do wiring and assembly work only on a voltage-free or grounded work mat. Failure to do this can lead to dangerous static charge from your body and to damage to the components.
- Operate the decoder only with the authorized voltage (see technical data).

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Technical Information

- Continuous current load at the motor output ≤ 1.1 amps .
- < 250 milliamps Current load at the light outputs .
- Current load at AUX 1 AUX 2 each \leq 250 milliamps . \leq 300 milliamps
- Current load at AUX + lights (total) .
- Current load for motor and AUX 5/6 .
- Maximum total load .

 \leq 1.6 amps < 40 volts

 \leq 1.1 amps

- Maximum voltage
- Sound performance (at 4 Ω /8 Ω) 2.3 watts / 1.2 watts
- Short circuit and overload protection at the outputs lights • front (LV), lights rear (LH), AUX 1 - AUX 2 and at the motor outputs.

Functions

.

The mSD SoundDecoder is a sound decoder with very extensive setting and adaptation possibilities. Additional sound functions are available. This decoder can be updated. The requirement for this is an appropriate controller (60213/60214/60215 Central Station, software Version 2.0, track format processor GFP 2.0 or higher).

The settings and digital functions can only be used in digital operation. However, the same possibilities are not available in all protocols.

These instructions describe the installation and the possible settings for the 60948 and 60949 decoders. Unless otherwise stated, the functions refer to both decoders.

- Capable of multi-protocols (fx (MM), mfx, DCC, and AC/DC). •
- Automatic system recognition. The address assigned to each system must be used for operation.

- Acceleration and braking delay can be set separately from each other. Any function button desired can be assigned using the function mapping.
- · Typical sound backdrops for diesel and electric locomotives are included.
- Variable motor feedback control is available in digital as well as in analog operation.
- 6090, 60901, DC, and can motors with bell-shaped armatures are supported. See necessarily this table on page 3. These locomotives can not be converted this set.
- Function mapping included.
- Can be updated with the CS2 (Software 2.0, track format processor GFP 2.0 or higher).
- Programming on the Main (PoM) this type of programming must be supported by the controller. Please note the instructions for your controller when doing this.
- Switching range can be set.
- Braking / signal stopping block recognition is available in digital operation.

Decoder Installation

The locomotive must be checked before installing the decoder to make sure that it (locomotive) is in good mechanical and electrical condition. There are situations when the locomotive will have to be repaired before installing the decoder.

Locomotives / Powered Rail Cars with a Connector

First unsolder the wires to the current pickups (pickup shoe(s)), motor, and the lights. After that remove the old decoder or reverse unit. Position the new decoder and solder the wires according to the diagram nearby.

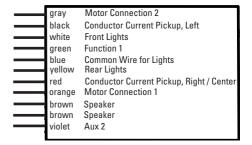
If the lights are grounded to the locomotive's or powered rail car's ground on the frame, we recommend that the lights be insulated from the locomotive ground. To do this, use the E604180 plug-in bulb holder(s) and E610080 light bulb(s). This will give you flicker-free lighting.

If your locomotive or powered rail car is equipped with LED lighting, then series resistors must absolutely be installed. Series resistors differ according to the current the design. Find out the correct values for your LEDs. You may have to ask your specialty dealer about this.

If you want to retrofit your locomotive or powered rail car with LEDs, the cathodes (-) on the LED are connected to the light output on the decoder. **Don't forget** series resistors! The anodes (+) are connected to the common wire (blue).

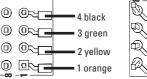
The common ground return (blue) must not be connected to the ground for the locomotive or powered rail car.

This procedure is identical for the 60965, 60966 and 60967 decoder. Make sure that you pay absolute attention to the **notes** for the **colors of the wires** for each decoder.



solder pad above





8 red 9 9 7 blue 9 9 6 white 9 9 5 gray

Locomotives or powered rail cars with NEM 8-pin connector.

Solder the wires to the correct solder pads according to the diagram above. The brown wire with the ends of speaker wire is soldered and insulated.

Insert the plug into the connector while paying attention to the positioning. Place the model, with the body left off, on the programming track and test it. If the decoder works with no problems, the body can be put on the locomotive.

Cross Referencing the Colors for the Wires

| Description | w | ire Color |
|------------------------------------------------------------|--------|-------------|
| | NEM | Märklin |
| Motor Connection 2 | gray | blue |
| Conductor Current Pickup, Track, Left (DC) Outer (AC) | black | brown |
| Front Lights | white | gray |
| Function 1 | green | brown/red |
| Common Wire for Lights | blue | orange |
| Rear Lights | yellow | yellow |
| Conductor Current Pickup, Track, Right (DC) Center (AC) | red | red |
| Motor Connection 1 | orange | green |
| Speaker + | brown | white |
| Speaker – | brown | white |
| Aux 2 (physical output) | violet | brown/green |

Multi-Protocol Operation

Analog Operation

This decoder can also be operated on analog layouts or areas of track that are analog. The decoder recognizes alternating current or direct current voltage (AC/DC) and automatically adapts to the analog track voltage. All functions that were set under mfx or DCC for analog operation are active (see Digital Operation).

Digital Operation

The mSD sound decoders are multi-protocol decoders. These decoders can be used under the following digital protocols: mfx, DCC, fx (MM).

The digital protocol with the most possibilities is the highest order digital protocol. The sequence of digital protocols in descending order is:

Priority 1: mfx Priority 2: DCC Priority 3: fx (MM)

Note: Digital protocols can influence each other. For troublefree operation, we recommend deactivating those digital protocols not needed by using CV 50. Deactivate unneeded digital protocols at this CV if your controller supports this function.

If two or more digital protocols are recognized in the track, the decoder automatically takes on the highest order digital protocol, example: mfx/DCC; the decoder takes on the mfx digital protocol (see previous table). **Note:** Please note that not all functions are possible in all digital protocols. Several settings for functions, which are supposed to be active in analog operation, can be done under mfx and DCC.

Braking / Signal Stopping Block (MM, fx, mfx)

The braking module essentially applies DC voltage to the track. If the decoder recognizes a DC voltage of this kind in the track, it brakes with the delay that has been set. If the decoder recognizes a digital protocol again, it accelerates at the speed that has been set.

If automatic recognition in braking areas is to be used, we recommend shutting the DC operation off (see CV description).

mfx Protocol

Addresses

- No address is required; each decoder is given a onetime, unique identifier (UID).
- The decoder automatically registers itself on a Central Station or a Mobile Station with its UID.

Programming

- The characteristics can be programmed using the graphic screen on the Central Station or also partially with the Mobile Station.
- All of the Configuration Variables (CV) can be read and programmed repeatedly.
- The programming can be done either on the main track or the programming track.

- The default settings (factory settings) can be produced repeatedly.
- Function mapping: Functions can be assigned to any of the function buttons with the help of the 60212 Central Station (with limitations) and with the 60213/60214/60215 Central Station (See help section in the Central Station).

fx (Motorola) Protocol

Addresses

- 4 addresses (a main address and 3 consecutive addresses)
- Address range:
 - 1 255 depending on the controller / central controller
- The main address can be programmed manually.
- The consecutive addresses can be turned on, turned off, set and can be programmed manually or automatically.
- All 16 functions can be controlled by means of the four addresses.

Programming

- The characteristics can be programmed for the decoder can be programmed repeatedly using the programming for the Configuration Variables (CV). Reading the CVs is not possible.
- The CV numbers and the CV values are entered directly.
- Program the CVs only on the programming track. (Seite 9, rechts Fortsetzung)
- The default settings (factory settings) can be produced repeatedly.
- 14 or 27 speed levels can be programmed.

- The first four functions and the lights can always be controlled by means of the first address; additional functions can be used, depending on the consecutive addresses.
- All of the settings from the function mapping for mfx or DCC programming are taken on for fx (Motorola).
- Automatic recognition corresponding to the active additional or consecutive addresses. What is recognized is whether the function can be turned on or off continuously by means of a consecutive address. This function mapping can only be determined in the mfx or DCC protocol.
- See the CV description for the fx protocol for additional information.

DCC Protocol

Addresses

- Short address long address multiple unit address
- · Address range:
 - 1 127 for short address and multiple unit address,
 - 1 10239 for long address
- Every address can be programmed manually.
- A short or a long address is selected using the CVs.
- A multiple unit address that is being used deactivates the standard address.

Programming

- The characteristics can be changed repeatedly using the Configuration Variables (CV).
- The CV numbers and the CV values are entered directly.
- The CVs can be read and programmed repeatedly. (Programming is done on the programming track.)

- The CVs can be programmed in any order desired. (Programming can be done on the main track PoM). The PoM can only be done with those designated in the CV table. Programming on the main track PoM must be supported by your central controller (Please see the description for this unit.).
- The default settings (factory settings) can be produced repeatedly.
- 14/28 or 126 speed levels can be set.
- All of the functions can be controlled according to the function mapping (see CV description).
- See the CV description for the DCC protocol for additional information.

We recommend that in general programming should be done on the programming track.

Physical Functions

Each of these functions must be connected externally to the circuit board. We therefore speak of physical functions. A unique mode/effect can be assigned to each physical output (AUX / lights) in digital operation. Three CVs are available for each output for this purpose. Only one mode/effect can be set for each output. A complete table for this can be found on the Internet at:

www.maerklin.de/de/produkte/tools_downloads/technische_infos.html

Logic Functions

Since these functions are only executed by software, no physical output is required for them. We therefore speak here of a logic function.

Acceleration/Braking Delay

- The acceleration and braking time can be set separately from each other.
- The logic function ABV can be assigned to any function button by using the function mapping.

Switching Range (RG)

 The switching range causes a reduction in the current speed of the locomotive. This allows a fine touch in the controlling the locomotive. The switching range can be assigned in mfx and DCC to any function button by using the function mapping.

Station Announcement

The locomotive does not go until after the announcement has ended.

Opening Doors / Closing Doors

The locomotive does not start running as long as the function "opening doors / closing doors" is active. The locomotive starts accelerating according to the ABV that has been set/activated only when the function has been deactivated and the sound has ended.

Decoder functions and CV settings

The following pages have the functions and the CVs presented in tabular form. These CVs can be given a number of settings and can be assigned to a number of function buttons.

You'll find the CVs and their applications for the track formats fx (MM) and DCC in separate tables.

The track format mfx can be easily set by using the display on the CS 2 with Software Version 2.0 and higher. You or your dealer may have to install an update on your 60213/60214/60215 Central Station.

We recommend following the procedures that are shown and described.

Decoder 60965

| Controllable Functions | | | | F0 F4 | Digital/Systems |
|-------------------------------------|--------------|------------|------------|--------------|-----------------|
| Headlights | function/off | Ś | ⊗ | Function f0 | Function f0 |
| Smoke generator (Aux1) | f1 | Function 1 | Function * | Function f1 | Function f1 |
| Sound effect: Operating sounds | f2 | Function 2 | Function * | Function f2 | Function f2 |
| Sound effect: Whistle blast | f3 | Function 3 | Function * | Function f3 | Function f3 |
| ABV off | f4 | Function 4 | Function * | Function f4 | Function f4 |
| Sound effect: Buffer to buffer | 1 | _ | Function * | Function f5 | Function f5 |
| Switching range + double A light | 1 | _ | Function * | Function f6 | Function f6 |
| Sound effect: Bell | _1 | | Function * | Function f7 | Function f7 |
| Telex coupler (Aux 2) | 1 | | Function * | Function f8 | Function f8 |
| Sound effect: Squealing brakes off | 1 | | _ | Function f9 | Function f9 |
| Sound effect: Coal being shoveled | 1 | — | _ | Function f10 | Function f10 |
| Sound effect: Short whistle blast | 1 | — | — | Function f11 | Function f11 |
| Sound effect: Station announcements | 1 | — | — | Function f12 | Function f12 |
| Sound effect: Rocker grate | _1 | _ | _ | Function f13 | Function f13 |
| Sound effect: Rail joints | _1 | | | Function f14 | Function f14 |
| Sound effect: Conductor whistle | 1 | | | Function f15 | Function f15 |

*Function and Function symbols may be displayed in different order.

Decoder 60966

| Controllable Functions | | | | | f0 f8 f8 f0 Digital/Systems |
|-------------------------------------|--------------|------------|------------|--------------|--------------------------------|
| Headlights | function/off | ¥ | A | Function f0 | Function f0 |
| Engineer's cab lighting (Aux 1) | f1 | Function 1 | Function * | Function f1 | Function f1 |
| Sound effect: Operating sounds | f2 | Function 2 | Function * | Function f2 | Function f2 |
| Sound effect: Horn 1 | f3 | Function 3 | Function * | Function f3 | Function f3 |
| ABV switching off | f4 | Function 4 | Function * | Function f4 | Function f4 |
| Sound effect: Coupling together | _1 | _ | Function * | Function f5 | Function f5 |
| Sound effect: Uncoupling | _1 | — | Function * | Function f6 | Function f6 |
| Sound effect: Horn 2 | _1 | _ | Function * | Function f7 | Function f7 |
| Telex coupler (Aux 2) | _1 | — | Function * | Function f8 | Function f8 |
| Sound effect: Squealing brakes off | _1 | — | _ | Function f9 | Function f9 |
| Sound effect: Blower | _1 | _ | _ | Function f10 | Function f10 |
| Sound effect: Bell | _1 | _ | _ | Function f11 | Function f11 |
| Sound effect: Station announcements | _1 | _ | _ | Function f12 | Function f12 |
| Sound effect: Auxiliary diesel | _1 | _ | _ | Function f13 | Function f13 |
| Sound effect: Rail joints | 1 | _ | _ | Function f14 | Function f14 |
| Sound effect: Conductor whistle | 1 | — | _ | Function f15 | Function f15 |

¹ can be controlled by using consecutive addresses

*Function and Function symbols may be displayed in different order.

Decoder 60967

| Controllable Functions | | | | | f0 f8 f8 f0 Digital/Systems |
|-------------------------------------|--------------|------------|------------|--------------|--------------------------------|
| Headlights | function/off | 1 | 8 | Function f0 | Function f0 |
| Long distance headlights (Aux 1) | f1 | Function 1 | Function * | Function f1 | Function f1 |
| Sound effect: Operating sounds | f2 | Function 2 | Function * | Function f2 | Function f2 |
| Sound effect: Horn 1 | f3 | Function 3 | Function * | Function f3 | Function f3 |
| ABV switching off | f4 | Function 4 | Function * | Function f4 | Function f4 |
| Sound effect: Buffer to buffer | 1 | — | Function * | Function f5 | Function f5 |
| Sound: Checking train tickets | 1 | _ | Function * | Function f6 | Function f6 |
| Sound effect: Horn 2 | 1 | — | Function * | Function f7 | Function f7 |
| Telex coupler (Aux 2) | _1 | _ | Function * | Function f8 | Function f8 |
| Sound effect: Squealing brakes off | _1 | — | _ | Function f9 | Function f9 |
| Sound effect: Blower | 1 | — | _ | Function f10 | Function f10 |
| Sound effect: Short whistle blast | 1 | _ | _ | Function f11 | Function f11 |
| Sound effect: Station announcements | 1 | | | Function f12 | Function f12 |
| Sound effect: Compressor | 1 | _ | _ | Function f13 | Function f13 |
| Sound effect: Rail joints | _1 | _ | _ | Function f14 | Function f14 |
| Sound effect: Conductor whistle | 1 | _ | _ | Function f15 | Function f15 |

*Function and Function symbols may be displayed in different order.

Volume

mfx protocol: The total volume for the sound functions can be changed easily with the 60213/60214/60215 Central Station in the CV menu "Sound". The function mapping (assigning the function buttons) and the individual volume settings are done with the function buttons. The sound number is required for the function mapping.

fx protocol: In the fx protocol only the total volume can be changed with CV 63. It is not possible to change the individual volumes. However, settings done under mfx or DCC are preserved.

DCC protocol: The volume can be changed by using the CVs below. The sound number is required for the function mapping and for the assignment of the CVs to the sound.

| | Sound-Nr. | | | | | | | |
|----------------------------|-----------|----------------|-----|----------------|-----|----------------|---------|---------|
| Sound functions | CV | Steam | CV | Diesel | CV | Electric | Default | Values |
| Total volume | 63 | all | 63 | all | 63 | all | 255 | 0 - 255 |
| Sound effect: Function f2 | 139 | Running sounds | 139 | Running sounds | 139 | Running sounds | 180 | 0 - 255 |
| Sound effect: Function f3 | 140 | 1 | 140 | 1 | 140 | 1 | 180 | 0 - 255 |
| Sound effect: Function f5 | 155 | 16 | 147 | 8 | 155 | 16 | 180 | 0 - 255 |
| Sound effect: Function f6 | — | — | 149 | 10 | 150 | 15 | 180 | 0 - 255 |
| Sound effect: Function f7 | 141 | 2 | 141 | 2 | 141 | 2 | 180 | 0 - 255 |
| Sound effect: Function f8 | — | — | — | — | — | — | | _ |
| Sound effect: Function f9 | 138 | Brake sounds | 138 | Brake sounds | 138 | Brake sounds | 180 | 0 - 255 |
| Sound effect: Function f10 | 148 | 9 | 148 | 9 | 148 | 9 | 180 | 0 - 255 |
| Sound effect: Function f11 | 142 | 3 | 142 | 3 | 142 | 3 | 180 | 0 - 255 |
| Sound effect: Function f12 | 143 | 4 | 144 | 5 | 144 | 5 | 180 | 0 - 255 |
| Sound effect: Function f13 | 149 | 10 | 146 | 7 | 150 | 11 | 180 | 0 - 255 |
| Sound effect: Function f14 | 153 | 14 | 153 | 14 | 153 | 14 | 180 | 0 - 255 |
| Sound effect: Function f15 | 144 | 5 | 145 | 6 | 145 | 6 | 180 | 0 - 255 |

| CV | Explanation | Values | Default | Notes |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|------------------------------|----------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 1 | Address 1 (main address) | 1-255 (1 - 80)* | 60965=78 60966=72 60967=24 | Address is always active and is not subject to CV 49 |
| 2 | Minimum speed (Vmin) | 1-255 (1 - 80)* | 5 | Speed at the smallest speed level. Value must be smaller than Vmax, CV 5. |
| 3 | Acceleration delay (AV) | 1-255 (1 - 80)* | 25 | CV value multiplied by 0.25 gives the time from complete stop to maximum speed. |
| 4 | Braking delay (BV) | 1-255 (1 - 80)* | 16 | CV value multiplied by 0.25 gives the time from Maximum speed to complete stop. |
| 5 | Maximum speed (Vmax) | 1-255 (1 - 63)* {x4}* | 255 | Speed at the highest speed level. Value must be greater than CV 2. |
| 8 | Decoder reset (default or factory setting) | 8 | | Value is not written. |
| 17 | Address 3 (2nd consecutive address) | 1-255 (1 - 80)* | 254 | Address can be deactivated/activated subject to CV 49. |
| 18 | Address 4 (3rd consecutive address) | 1-255 (1 - 80)* | 253 | Address can be deactivated/activated subject to CV 49. |
| 27 | Braking mode: Bit 0 - 3 : always 0, Bit 4 : DC voltage, polarity against the direction of travel Bit 5 : DC voltage, polarity with the direction of travel Bit 6 - 7 : always | 0 - 48 0 16 32 0 | 48 | Braking subject to direction: - 16 normal DCC properties - 32 inverse DCC properties Braking not subject to direction: - 48: fx/mfx properties |

* () = 6021 Control Unit $\{ \}$ = the values entered are multiplied times "x" (factor).

| CV | Explanation | Values | Default | Notes |
|----|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 29 | Configuration: Bit 0: Reverse the locomotive's direction properties 0 = normal direction 1 = invert direction Bit 1: number of speed levels half levels 14 or 27 0 = 14 speed levels 1 = 27 speed levels Bit 2: turn analog operation on/off 0 = analog off, 1 = analog on | 0 - 7 | 6 | The direction properties refer to the direc- tion of travel and the lights. The number of speed levels and half levels depend on the locomotive controller. Only digital operation or also conventional operation. Flipping back and forth between the modes is possible during operation. |
| 49 | Expanded configuration: Bit 0: number of addresses, LSB Bit 1: number of addresses, MSB Bit 2: automatic consecutive addressing (on / 1=off) | 0 - 7 | 5 | $\begin{array}{l} 0 = one \mid 1 = two \mid 0 = three \mid 1 = four \\ 0 \; Add. \mid 0 \; Add. \mid 1 \; Add. \mid 1 \; Add. \\ 0 = auto. \; sequence \; on \; / \; 1 = auto. \; sequence \; off \end{array}$ |
| 50 | Alternative formats: Bit 0: analog AC off = 0 / analog AC one = 1 Bit 1: analog DC off = 0 / analog DC on = 1 Bit 2: DCC off = 0 / DCC on = 1 Bit 3: mfx off = 0 / mfx on = 1 | 0 - 15 | 15 | Note: fx (Motorola) cannot deactivate itself |

* () = 6021 Control Unit $\}$ = the values entered are multiplied times "x" (factor).

| CV | Explanation | Values | Default | Notes |
|----|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------|---------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 52 | Motor type (Bit 0-4) Auxillary function outputs 5 and 6 Motor – Softdrive Sine Motor – without feedback control Motor – High efficiency propulsion C90 Motor – Bell armature Motor – direct current DC soft Motor – direct current DC hard Motor – direct current DC 1 Gauge also analog with feedback control 0: with analog with feedback control 1: without analog with feedback control | 0 - 63 0 1 2 3 4 5 6 7 7 0 32 | 3 | Selection of a motor type for addi- tional settings for motor feedback control. or Selection of additional function outputs on an H0 decoder. See extra table ¹ for how motor outputs work as additional auxiliary functions. |
| 53 | Motor feedback control – feedback control reference | 1 - 255 (0 - 63)* {x4}* | 150 | Absolute Vmax for motor characte- ristic |
| 54 | Motor feedback control – feedback control parameter K | 1 - 255 (0 - 63)* {x4}* | 64 | Feedback control portion P |
| 55 | Motor feedback control – feedback control parameter I | 1 - 255 (0 - 63)* {x4}* | 64 | Feedback control portion I |
| 56 | Motor feedback control – feedback control influence | 1 - 255 (0 - 63)* {x4}* | 24 | 0 = PWM without feedback control for Sine (see also CV 52 motor type) |
| 57 | Steam locomotive sound interval of the steam chuffing at speed level 1 | 1 - 255 (0 - 63)* {x4}* | 46 | without a wheel sensor |
| 58 | Steam locomotive interval of the steam chuffing starting at speed level 2, | 1 - 255 (0 - 63)* {x4}* | 95 | without a wheel sensor |
| 63 | Total volume | 1 - 255 (0 - 63)* {x4}* | 255 | Total volume for all sounds. 0 = no sound |

* () = 6021 Control Unit {} = the values entered are multiplied times "x" (factor).

* An extensive table for function mapping can be found on the Internet at: www.maerklin.de/de/produkte/tools_downloads/technische_infos.html

| CV | Explanation | Values | Default | Notes |
|----|------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------|----------------------------------|---------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 64 | Threshold for brake squealing | 1 - 255 (0 - 63)* {x4}* | 55 | The higher the value the sooner the squealing begins, the lower the value the later the squealing begins. If the value is too low, no squealing is activated. |
| 73 | Storing different states: Bit 0: storing function states Bit 1: storing speed Bit 2: starting up with/without ABV after a reset | 0 - 7 0 / 1 0 / 2 0 / 4 | 7 | 0 = do not store / 1 = store 0 = do not store / 2 = store 0 = without ABV / 4 = with ABV |
| 74 | Storing different states: Bit 0: storing direction of travel | 0 - 1 | 1 | 0 = do not store / 1 = store |
| 75 | Address 2 (1st consecutive address) | 1 - 80 | 60965=79 60966=73 60967=25 | Address can be activated/deactivated subject to CV 49. |
| 76 | Analog DC startup voltage | 1 - 63 {x4}* | 100 | Note for CS1: (140) The CS1 shows this value inverted. |
| 77 | Analog DC maximum speed | 1 - 63 {x4}* | 255 | |
| 78 | Analog AC startup voltage | 1 - 63 {x4}* | 100 | Note for CS1: (140) The CS1 shows this value inverted. |
| 79 | Analog AC maximum speed | 1 - 63 {x4}* | 255 | |

* () = 6021 Control Unit {} = the values entered are multiplied times "x" (factor).

| CV | Explanation | Values | Default | Notes |
|-------------------|--------------------------------------------------------------------------------|-----------|-------------------------------|-----------------------------------------------------------------------------------------------|
| 1 | Main address | 1 - 127 | 3 | Short address 1 - 127 If CV 29 / Bit 5 = 0 |
| 2 ^{PoM} | Minimum speed (Vmin) | 0 - 255 | 5 | Value must be lower than Wert muss Vmax, CV 5. (see CV 67) |
| 3 ^{PoM} | Acceleration delay (AV) | 0 - 255 | 25 | CV value multiplied by 0.9 gives the time from being stopped to maximum speed. |
| 4 ^{PoM} | Braking delay (BV) | 0 - 255 | 16 | CV value multiplied by 0.9 gives the time from maximum speed to being stopped. |
| 5 PoM | Maximum speed (Vmax) | 0 - 255 | 255 | Speed at the highest speed level. Value must be higher than Vmin, CV 2.(see also CV 94) |
| 7 | Manufacturer's version number (software version) | | | Read only |
| 8 | Manufacturer identification / ID Decoder reset (default or factory setting) | - 8 | 131 | Read only Value cannot be read |
| 13 ^{PoM} | Functions F1 - F8 with an alternative track signal | 0 - 255 | 60965=1 60966=0 60967=0 | 0 = Func. MM or analog off 1 = Func. MM or analog on [F8 F7 F6 F5 F4 F3 F2 F1] |
| 14 ^{PoM} | Functions FL, F9 - F15 with an alternative track signal | 0 - 255 | 1 | 0 = Func. MM or analog off 1 = Func. MM or analog on [F15 F14 F13 F12 F11 F10 F9 FL] |
| 17 | Expanded address, higher value byte | 192 - 231 | 192 | Long address 1 - 10239 (128) |
| 18 | Expanded address, lower value byte | 0 - 255 | 128 | If CV 29 / Bit 5 = 1 |

PoM ("Programming on Main") must be supported by the locomotive controller / central controller.

| CV | Explanation | Values | Default | Notes |
|-------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|--------------------------------------|---------|-------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 19 | Multiple unit address | 0 - 255 | 0 | 1 - 127 = multiple unit address 0 = no multiple unit +128, Bit 7 = reverse polarity for direction when using multiple unit |
| 21 ^{PoM} | Functions F1 - F8 when using multiple unit | 0 - 255 | 0 | 0 = func. # only for locomotive address 1 = func. # also for multiple unit address Bit 7-0 = [F8 F7 F6 F5 F4 F3 F2 F1] |
| 22 ^{PoM} | Functions FL, F9 - F15 when using multiple unit | 0 - 255 | 0 | 0 = func. # only for locomotive address 1 = func. # also for multiple unit address Bit 7-0 = [F15 F14 F13 F12 F11 F10 F9 FL] |
| 27 ^{PoM} | Braking mode: Bit 0 - 3 : always 0, Bit 4 : DC voltage, polarity against the direction of travel Bit 5 : DC voltage, polarity with the direction of travel Bit 6 - 7 : | 0 - 48 0 0 / 16 0 / 32 0 | 48 | Braking subject to direction: - only Bit 4 : normal DC properties - only Bit 5 : inverse DC properties Braking not subject to direction: - Bit 4 + 5 : 3 rail properties |
| 29 ^{PoM} | Configuration: Bit 0 : reverses direction properties of the locomotive 0 = normal direction, 1 = inverse direction Bit 1 : speed level 14 or select 28/128 0 = 14 speed levels, 1 = 28/128 speed levels Bit 2 : turn analog operation off/on 0 = analog off, 1 = analog on Bit 5 : select short / long address 0 = short address, 1 = long address | 0 - 39 0/1 0/2 0/4 0/32 | 6 | The direction properties refer to the direction of travel and the lights. The number of speed levels and the light bit depend on the locomotive controller. Either the short main address or the long expanded address as a locomotive address. |

PoM must be supported by the locomotive controller / central controller.

| CV | Explanation | Values | Default | Notes |
|-------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 50 ^{PoM} | Alternative formats: Bit 0 : Analog AC off = 0 / Analog AC on = 1 Bit 1 : Analog DC off = 0 / Analog DC on = 1 Bit 2 : fx (MM) off = 0 / fx (MM) on = 1 Bit 3 : mfx off = 0 / mfx on = 1 | 0 - 15 0 / 1 0 / 2 0 / 4 0 / 8 | 15 | Note: DCC cannot deactivate itself. |
| 52 ^{PoM} | Motor type (Bit 0-4) Auxiliary – function outputs 5 and 6 Motor – Softdrive Sine Motor – without feedback control Motor – high-efficiency C90 Motor – bell armature Motor – direct current DC soft Motor – direct current DC hard Motor – direct current DC 1 Gauge also analog with feedback control 0 : with analog with feedback control 1 : without analog feedback control | 0 - 63 0 1 2 3 4 5 6 7 7 0 32 | 3 | Selection of a motor type for additional settings for motor feedback control or Selection of additional function outputs on an H0 decoder. See extra table for how motor outputs work as additional auxiliary functions. |
| 53 ^{PoM} | Motor feedback control – feedback control reference | 0 - 255 | 150 | Absolute Vmax for motor characteristic |
| 54 ^{PoM} | Motor feedback control – feedback control parameter K | 0 - 255 | 64 | Feedback control portion P |
| 55 ^{PoM} | Motor feedback control – feedback control parameter I | 0 - 255 | 64 | Feedback control portion I |
| 56 ^{PoM} | Motor feedback control – feedback control influence | 0 - 255 | 24 | 0 = PWM without feedback control for Sine (see also CV 52 motor type) |
| 57 ^{PoM} | Steam locomotive sound interval of the steam chuffing at speed level 1 | 1 - 255 (0 - 63)* {x4}* | 46 | without a wheel sensor |
| 58 ^{PoM} | Steam locomotive interval of the steam chuffing star- ting at speed level 2, | 1 - 255 (0 - 63)* {x4}* | 95 | without a wheel sensor |
| 63 ^{PoM} | Total volume | 0 - 255 | 255 | Total volume for all sounds. 0 = no sound |

PoM must be supported by the locomotive controller / central controller.

| CV | Explanation | Values | Default | Notes |
|----------------------------------------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------|------------------------------|-----------------------------------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| 64 ^{PoM} | Brake squealing threshold | 0 - 255 | 60965=105 60966=55 60967=55 | The higher the value the sooner the squealing begins, the lower the value the later the squealing begins. If the value is too low, no squealing is activated |
| 66 ^{PoM} | Forward trim | 0 - 255 | 128 | The CV value divided by 128 gives the fac- tor with the speed level is multiplied when the locomotive is running forward. |
| 67 ^{PoM} | Speed table speed level 1 (Vmin) to | 0 055 | | |
| - 94 ^{PoM} | speed table speed level 28 (Vmax) | 0 - 255 | | |
| 95 ^{PoM} | Reverse trim | 0 - 255 | 128 | The CV value divided by 128 gives the fac- tor with the speed level is multiplied when the locomotive is running in reverse. |
| 112 ^{PoM} 113 ^{PoM} 114 ^{PoM} | Physical output (mapping): front light mode Physical output (mapping): front light dimmer Physical output (mapping): front light period | 0 - 16 0 - 255 0 - 255 | 1 255 20 | See table* |
| bis 135 ^{PoM} | Physical output (mapping): rear light, Aux 1 to Aux 6 (each one in the 3rd block) | | | See table* |
| 137 ^{PoM} | Switching range | 0 - 128 | 128 | 128 = 50% of speed level, 64 = 25% of speed level |

PoM must be supported by the locomotive controller / central controller.

* An extensive table for function mapping can be found on the Internet at: www.maerklin.de/de/produkte/tools_downloads/technische_infos.html

| CV | Explanation | Values | Default | Notes |
|-------------------------------------------------------------------------------------------|------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-----------------------------------------------------|--------------------------|---------------------------------------------------------------------|
| 138 ^{PoM} 139 ^{PoM} 140 ^{PoM} - 155 ^{PoM} | Sound output: Brake squealing (volume) Sound output: Volume of running sounds Sound output: Volume for Sound 1 up to Sound output: Volume for Sound 16 | 0 - 255 0 - 255 0 - 255 0 - 255 0 - 255 | 180 180 180 180 | 0 = no sound |
| 173 ^{PoM} | Storing different states: Bit 0: Storing function states Bit 1: Storing speed Bit 2: After a reset starting up with/without ABV Bit 3 - 7: always 0 | 0 / 1 0 / 2 0 / 4 | 7 | 0 = do not store, value = store Individual values must be added. |
| 174 ^{PoM} | Storing different states: Bit 0: Storing direction of travel Bit 1 - 7: always 0 | 0/1 | 1 | 0 = do not store 1 = store |
| 176 ^{PoM} | Vmin Analog DC | 0 - 255 | 100 | Must be smaller than CV 177 |
| 177 ^{PoM} | Vmax Analog DC | 0 - 255 | 255 | Must be larger than CV 176 |
| 178 ^{PoM} | Vmin Analog AC | 0 - 255 | 100 | Must be smaller than CV 179 |
| 179 ^{PoM} | Vmax Analog AC | 0 - 255 | | Must be larger than CV 178 |
| 257 ^{PoM} 258 ^{PoM} 259 ^{PoM} 260 ^{PoM} | Function assignment (mapping): Function FL forward A Function assignment (mapping): Function FL forward B Function assignment (mapping): Function FL forward C Function assignment (mapping): Function FL forward D | 0 - 255 0 - 255 0 - 255 0 - 255 0 - 255 | 1 0 0 0 | See table* |
| bis 445 | Function assignment (mapping): drive backward D | | | See table** |

PoM must be supported by the locomotive controller / central controller.

* An extensive table for function mapping can be found on the Internet at: www.maerklin.de/de/produkte/tools_downloads/technische_infos.html

Troubleshooting.

When operating with different protocols you may have problems in each mode at the same time. – We recommend reducing the number of protocols. Deactivate protocols in the locomotive decoder that are not needed and also deactivate if possible protocols in the central controller that are not needed.

The locomotive jerks and falters – Check the CV setting for motor variations, change if necessary, or carry out a reset to the factory settings.

The locomotive does not run in analog. – The automatic analog recognition is deactivated and must be activated again (see CV table).

The locomotive (decoder) does not react. – Check the wiring and the solder joints, redo if necessary. Check the connector for the decoder to make sure it has permanent contact and check the way it was installed.

mfx/DCC operation: Locomotives standing on the layout start running suddenly during mfx registration. – Deactivate the automatic analog recognition on these locomotives.

The locomotive does not run. – The function "open doors / close doors" is still active. Turn off the function "close doors"; after the sound ends the locomotive will run according to the ABV that has been set.

Disposing



Products marked with a trash container with a line through it may not be disposed of at the end of their useful life in the normal household trash. They must be taken to a collection point for the recycling of electrical and electronic devices. There is a symbol on

the product, the operating instructions, or the packaging to this effect. The materials in these items can be used again according to this marking. By reusing old devices, materially recycling, or recycling in some other form of old devices such as these you make an important contribution to the protection of our environment. Please ask your city, town, community, or county authorities for the location of the appropriate disposal site.

Warranty

The warranty card included with this product specifies the warranty conditions.

 Please contact your authorized M\u00e4rklin dealer for repairs or contact:

U.S. only: Wm. K. Walthers Inc. 5601 W. Florist Ave. Milwaukee, WI 53218

GB only

Gebr. Märklin & Cie. GmbH Reparaturservice Stuttgarter Str. 55 - 57 73033 Göppingen Deutschland Tel: +49 7161 608 222 E-Mail: Service@maerklin.de

| My personal decoder settings | | | |
|------------------------------|------|--|--|
| Locomotive: | | | |
| Adress | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |

| My personal decoder settings | | | |
|------------------------------|------|--|--|
| Locomotive: | | | |
| Adress | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |
| CV - | CV - | | |

This device complies with Part 15 of the FCC Rules. Operation is subject to the following two conditions:

- (1) This device may not cause harmful interference, and
- (2) this device must accept any interference received, including interference that may cause undesired operation.

Your local authorized Märklin dealer: www.RJFtrains.com e-mail: RJFtrains@aol.com Phone: 914-232-5546

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